



Ultimate Robot Kit

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Ultimate Robot Kit:

Ultimate Robotics Programming with ROS 2 and Python: Design, Develop, and Implement Intelligent Robotics Applications with Advanced Navigation, Simulation, and Computer Vision for Mobile and Industrial Robots

Jonathan Cacace, 2024-12-30 Learn Robotics and ROS 2 with Practical Examples Key Features Solve basic and complex robotics problems through practical examples Master ROS 2 programming fundamentals with Python for robotics Simulate mobile and industrial robots using modern Gazebo tools Book Description Robot Operating System ROS and Python are essential tools for developing advanced robotics applications offering reliability and scalability for both research and industrial solutions Ultimate Robotics Programming with ROS 2 and Python introduces readers to ROS 2 without requiring prior experience in robotics It blends theoretical explanations with practical exercises empowering readers to solve specific robotics problems while understanding the reasoning behind various approaches The book covers a broad spectrum of robotics topics including mobile robots industrial manipulators and aerial robots These systems are simulated using the modern Gazebo simulator and programmed with ROS 2's out of the box tools and custom solutions using the ROS 2 API The book also delves into computer vision generative AI and machine learning providing hands on examples of real world applications With intermediate challenges designed to reinforce learning this book serves as an all encompassing guide for anyone looking to master robotics programming with ROS 2 and Python Step into the future of robotics and gain the expertise to build sophisticated real world robotic systems that can tackle the complex challenges of tomorrow What you will learn Understand the fundamentals of ROS 2 for robotics development Develop robotics applications using Python and ROS 2 programming Master advanced ROS 2 packages for navigation and manipulation Implement behavior trees in ROS 2 with Python for intelligent robots Utilize modern Gazebo for realistic robot simulation with ROS 2 Integrate Large Language Models LLMs with ROS 2 for advanced functionalities Perform computer vision tasks with ROS 2 for intelligent robots Table of Contents 1 Introduction to Robot Operating System 22 Hands on ROS 2 Programming Using Python 3 Supplementary Tools for ROS 24 Robot Visualization and Simulation 5 Writing Tests Using Pytest for ROS 2 Nodes 6 Controlling an Inverted Pendulum with a PID Controller 7 Laser based Obstacle Avoidance with a Wheeled Mobile Robot 8 ROS 2 Behaviour Trees Using Python 9 Surveillance System Using Behaviour Trees 10 Robot Navigation Using ROS 2 Navigation Stack Nav2 11 Robot Arm Control Using MoveIt 212 Programming Aerial Robots Using ROS 213 Computer Vision Using ROS 214 Object Detection Using ROS 215 Using Large Language Models with ROS 216 Deep Reinforcement Learning Using ROS 2 Index

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