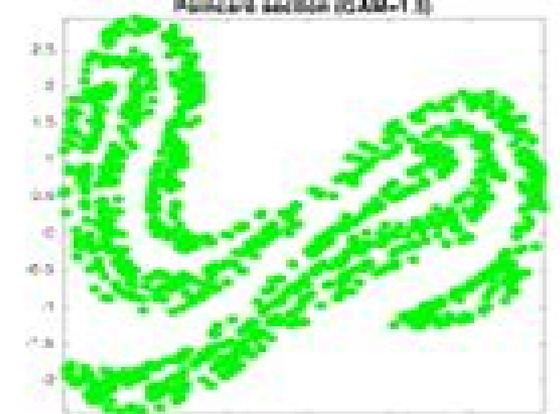
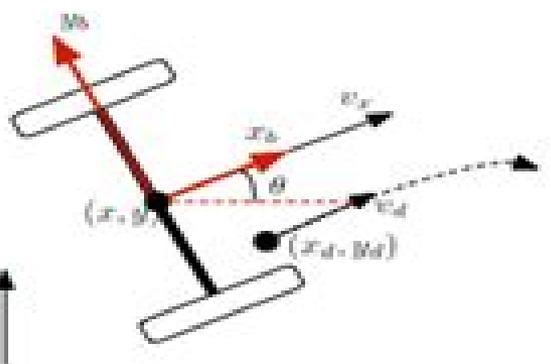


Figure 1. Mechanical interpretation of Duffing oscillator.



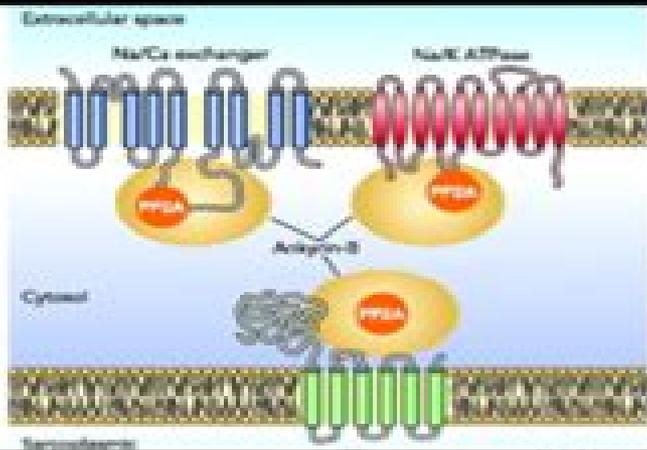
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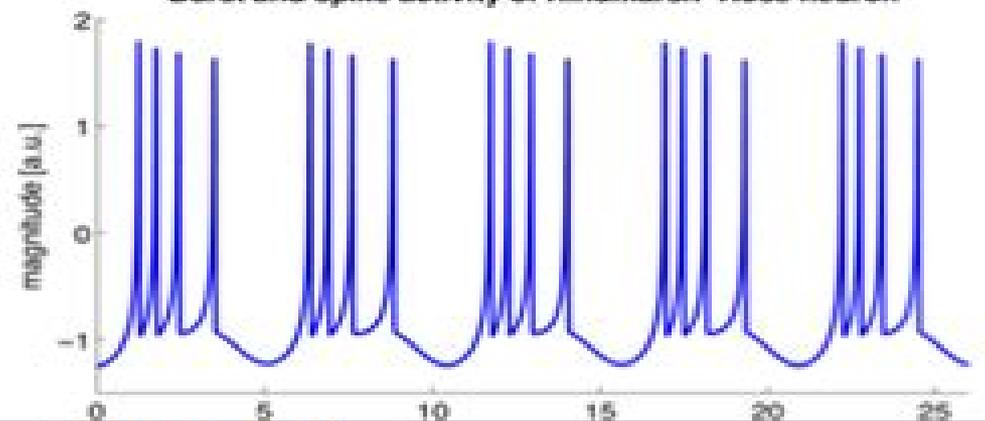
$$\begin{aligned} \dot{x} &= v_x \cos \theta \\ \dot{y} &= v_x \sin \theta \\ \dot{\theta} &= \omega \\ \dot{v}_x &= F \\ \dot{\omega} &= T \end{aligned}$$



Nonholonomic Systems



Burst and spike activity of Hindmarsh-Rose neuron



Bursting in Biological Systems

Theory Of Nonlinear Control Systems

**M. Kanat Camlibel,A. Agung
Julius,Ramkrishna
Pasumarthu,Jacquelien M.A. Scherpen**

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modern nonlinear control theory to practical engineering control designs Mathematical System Theory Athanasios C. Antoulas, 2013-04-17 Over the past three decades R E Kalman has been one of the most influential personalities in system and control theory His ideas have been instrumental in a variety of areas This is a Festschrift honoring his 60th birthday It contains contributions from leading researchers in the field giving an account of the profound influence of his ideas in a number of areas of active research in system and control theory For example since their introduction by Kalman in the early 60 s the concepts of controllability and observability of dynamical systems with inputs have been the corner stone of the great majority of investigations in the field

Control Systems Jitendra R. Raol, Ramakalyan Ayyagari, 2019-07-12 **Control Systems** Classical Modern and AI Based Approaches provides a broad and comprehensive study of the principles mathematics and applications for those studying basic control in mechanical electrical aerospace and other engineering disciplines The text builds a strong mathematical foundation of control theory of linear nonlinear optimal model predictive robust digital and adaptive control systems and it addresses applications in several emerging areas such as aircraft electro mechanical and some nonengineering systems DC motor control steel beam thickness control drum boiler motion control system chemical reactor head disk assembly pitch control of an aircraft yaw damper control helicopter control and tidal power control Decentralized control game theoretic control and control of hybrid systems are discussed Also control systems based on artificial neural networks fuzzy logic and genetic algorithms termed as AI based systems are studied and analyzed with applications such as auto landing aircraft industrial process control active suspension system fuzzy gain scheduling PID control and adaptive neuro control Numerical coverage with MATLAB is integrated and numerous examples and exercises are included for each chapter Associated MATLAB code will be made available

Geometric Theory of Nonlinear Control Systems, **Bilinear Control Systems** David Elliott, 2009-09-01 The mathematical theory of control became a field of study half a century ago in attempts to clarify and organize some challenging practical problems and the methods used to solve them It is known for the breadth of the mathematics it uses and its cross disciplinary vigor Its literature which can be found in Section 93 of Mathematical Reviews was at one time dominated by the theory of linear control systems which mathematically are described by linear differential equations forced by additive control inputs That theory led to well regarded numerical and symbolic computational packages for control analysis and design Nonlinear control problems are also important in these either the underlying dynamical system is nonlinear or the controls are applied in a non additive way The last four decades have seen the development of theoretical work on nonlinear control problems based on differential manifold theory nonlinear analysis and several other mathematical disciplines Many of the problems that had been solved in linear control theory plus others that are new and distinctly nonlinear have been addressed some resulting general definitions and theorems are adapted in this book to the bilinear case

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