

Control Theory

Control Theory, an interdisciplinary field, manages dynamical systems through feedback loops and control systems. Key concepts include PID controllers, while applications span industrial automation, aerospace engineering, and robotics. Control techniques encompass optimal, adaptive, and robust control. Feedback types include positive and negative feedback. Challenges involve modeling complexity, noise, and nonlinearity in control systems.



Theory And Application Of Digital Control

Nesim Halyo



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Theory and Application of Digital Control A. K. Mahalanabis, 2014-05-20 Theory and Application of Digital Control contains the proceedings of the IFAC Symposium held at New Delhi India on January 5-7 1982 This book particularly presents the texts of the five plenary talks and the 110 papers of the symposium This book organizes the papers into 109 chapters with nearly one third of the papers focus on digital control particularly software and hardware of control using microcomputers computer aided design and adaptive control and modeling for digital control Another set of papers deal with several applications of digital control techniques in solving interesting problems of socio economic systems electrical power systems bio systems and artificial satellites The reader will benefit hugely from the topics in this book that span several important theoretical and applied areas of the fast changing topic of digital control

Digital Control Systems Ioan Doré Landau, Gianluca Zito, 2007-05-11 The extraordinary development of digital computers microprocessors microcontrollers and their extensive use in control systems in all fields of applications has brought about important changes in the design of control systems Their performance and their low cost make them suitable for use in control systems of various kinds which demand far better capabilities and performances than those provided by analog controllers However in order really to take advantage of the capabilities of microprocessors it is not enough to reproduce the behavior of analog PID controllers One needs to implement specific and high performance model based control techniques developed for computer controlled systems techniques that have been extensively tested in practice In this context identification of a plant dynamic model from data is a fundamental step in the design of the control system The book takes into account the fact that the association of books with software and on line material is radically changing the teaching methods of the control discipline Despite its interactive character computer aided control design software requires the understanding of a number of concepts in order to be used efficiently The use of software for illustrating the various concepts and algorithms helps understanding and rapidly gives a feeling of the various phenomena

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